

High-Performance Mixed-Signal Controllers for On-Chip Integrated SMPS

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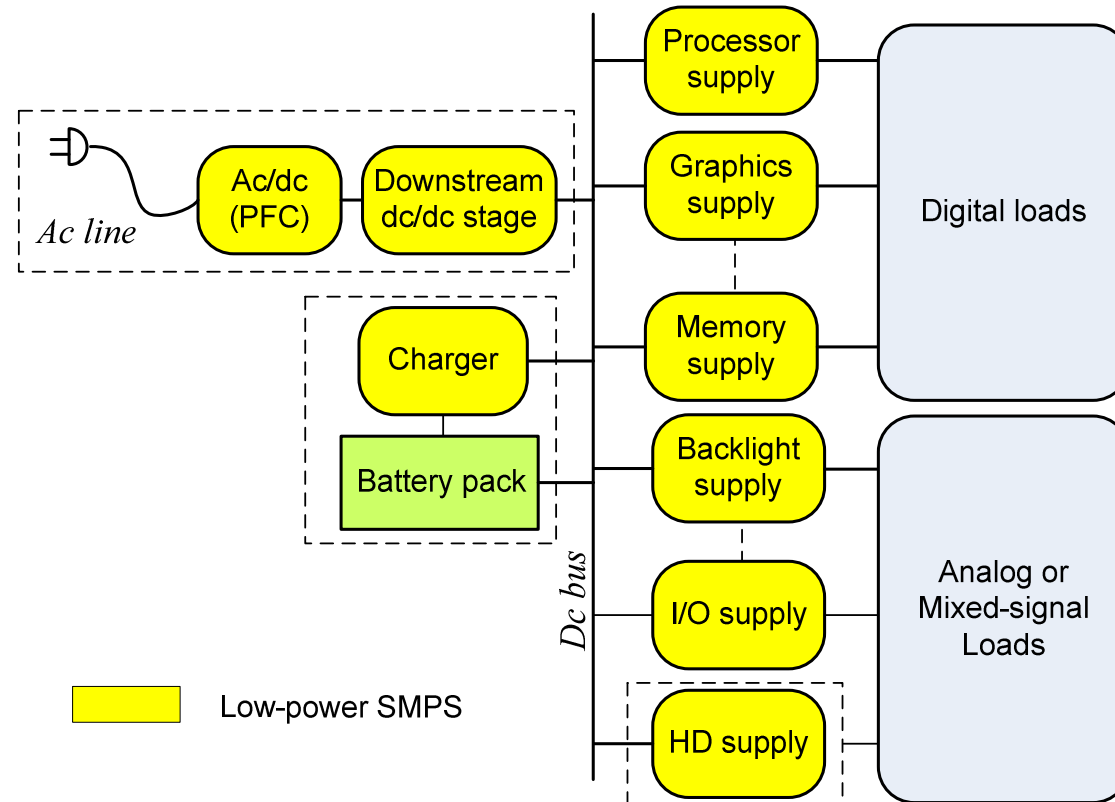
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Introduction

- *Volume occupied by low-power SMPS in today's applications*
- *On-chip implementation challenges*
- *Mixed-signal control method for **system (overall application) minimization***
 - *Ultra high frequency digital control*
 - *Minimum deviation control*
 - *Load interactive SMPS*



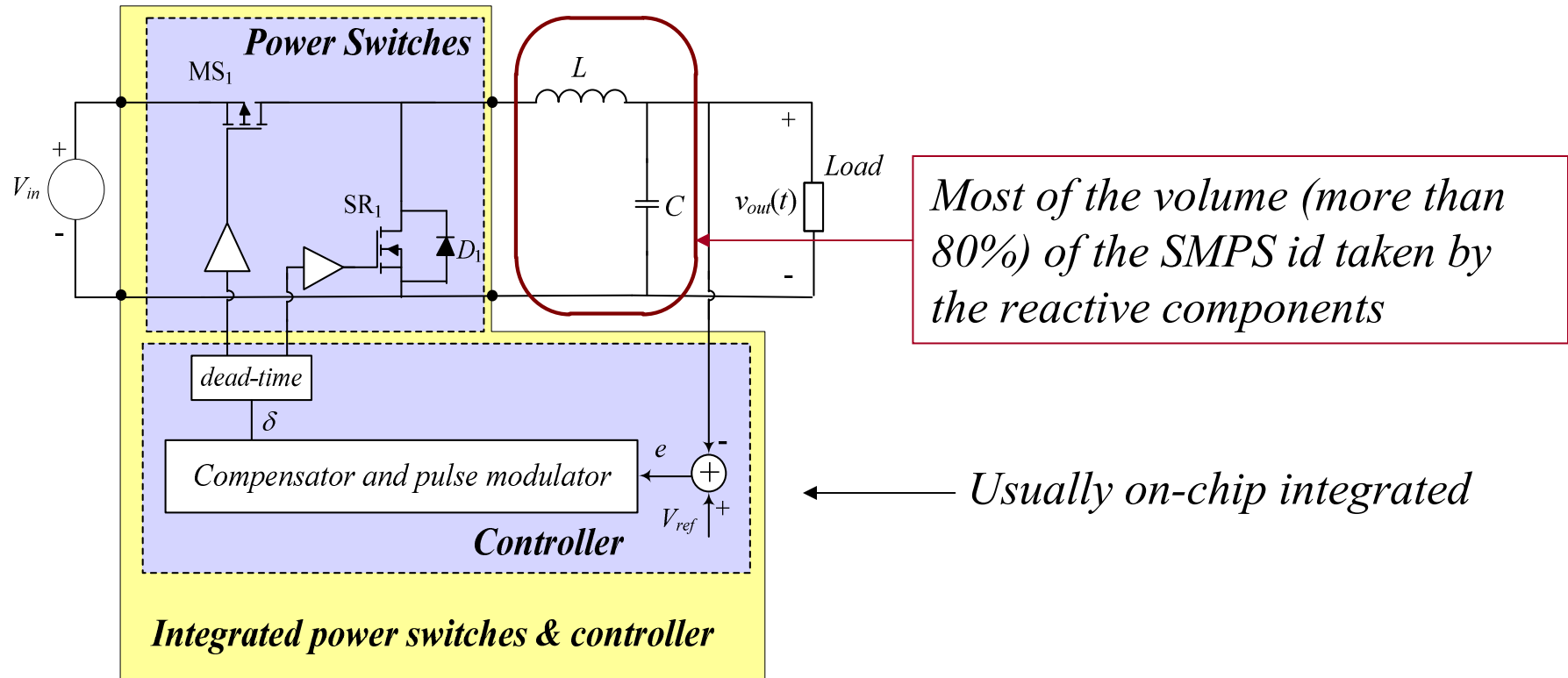
Low-Power Switch Mode Power Supplies (SMPS)



- *Power from a fraction of a watt to hundreds of watts*
- *Usually parts of a multi-supply power management systems*
- *Partially integrated and often take up to 30% of the total device volume/area*



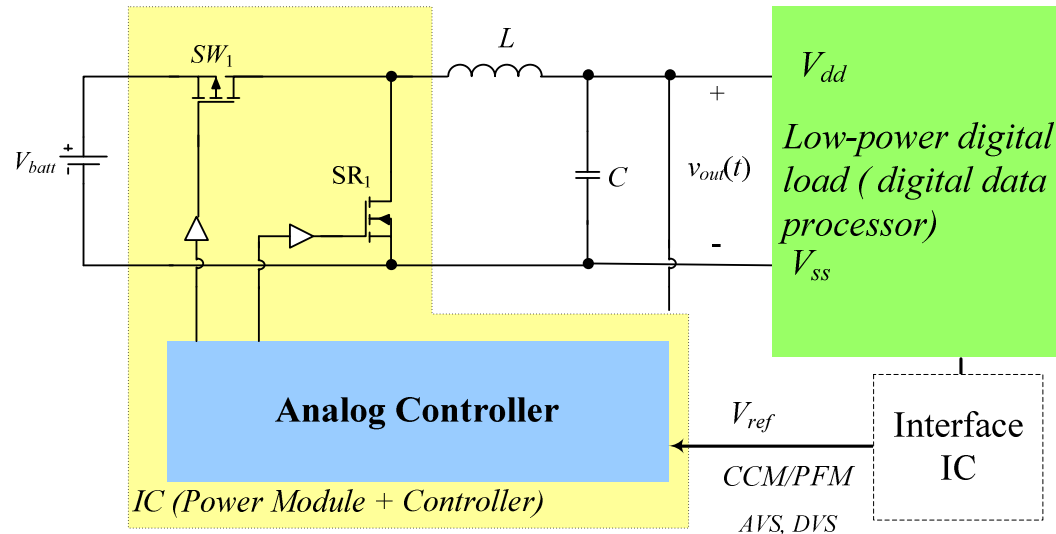
Volume/area Taken by the Reactive Components



More than a 25% of the motherboard (or other device) can be taken by the LC components of the SMPS



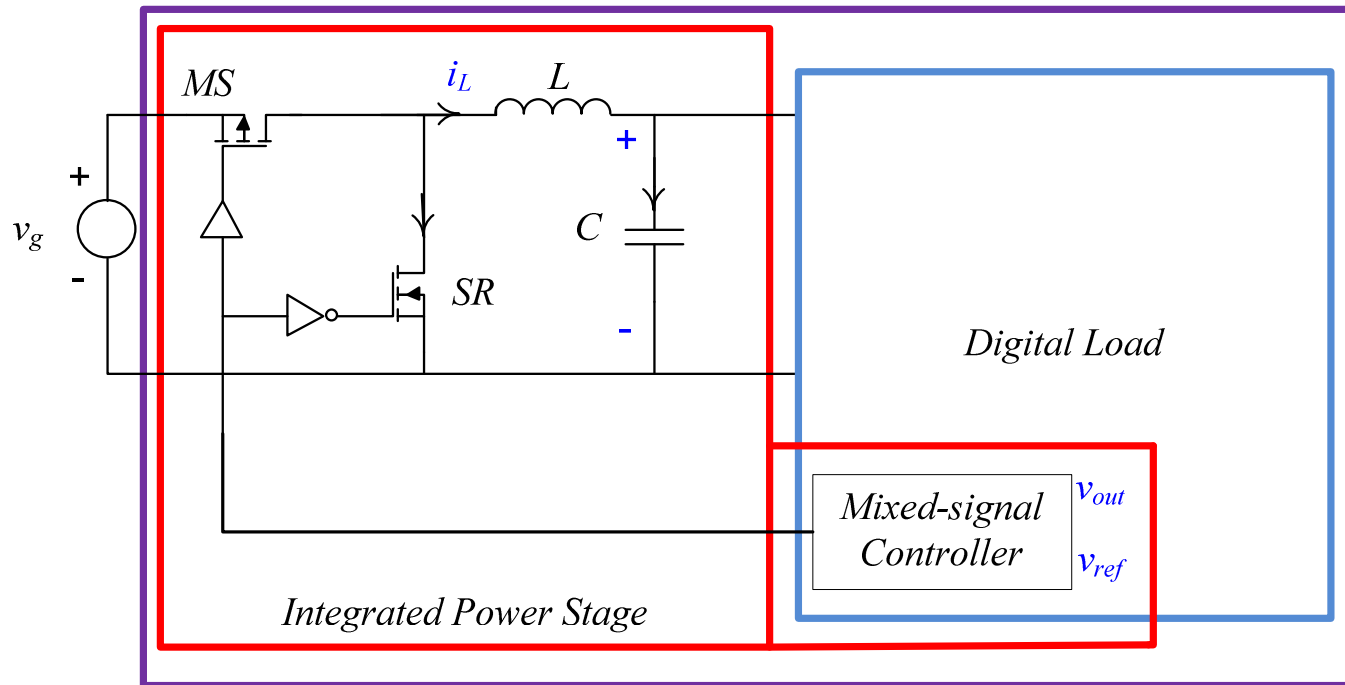
Reliability and Size Issues: Existing 3-Chip Solutions



- *Three chip solutions implemented in different technologies usually used (low flexibility, significant size, reliability, pin count...)*
- *Difficulties in implementing power management techniques such as dynamic and adaptive voltage scaling (AVS/DVS)*



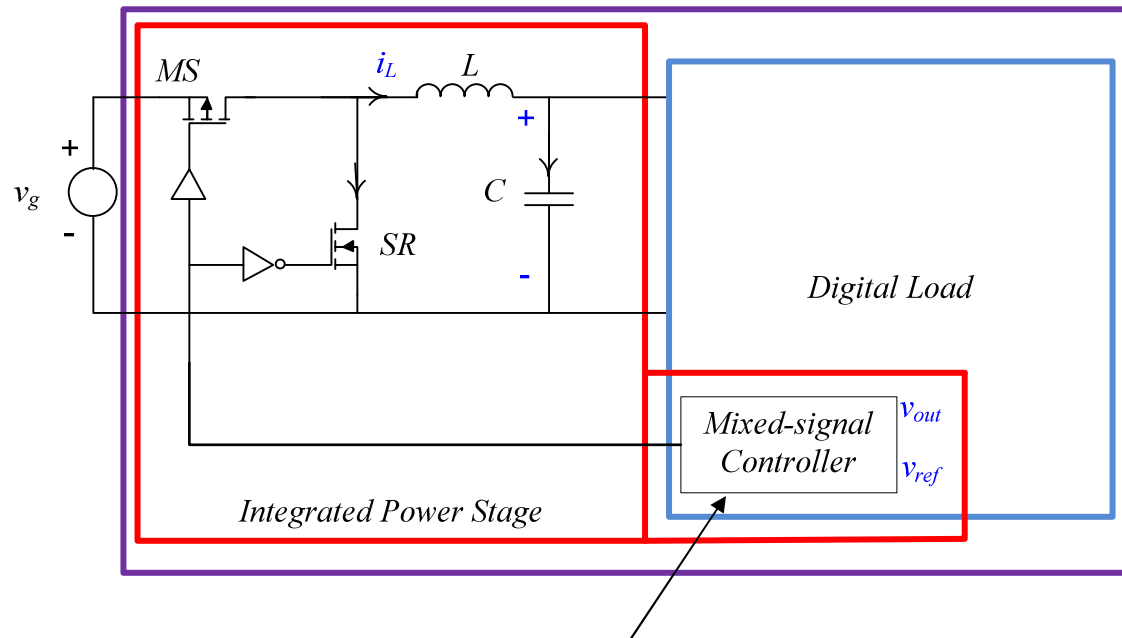
System Level Architecture



- *Two or a single chip solution for system integration*
- *Mixed-signal controller enables system minimization*



Mixed-Signal Controller

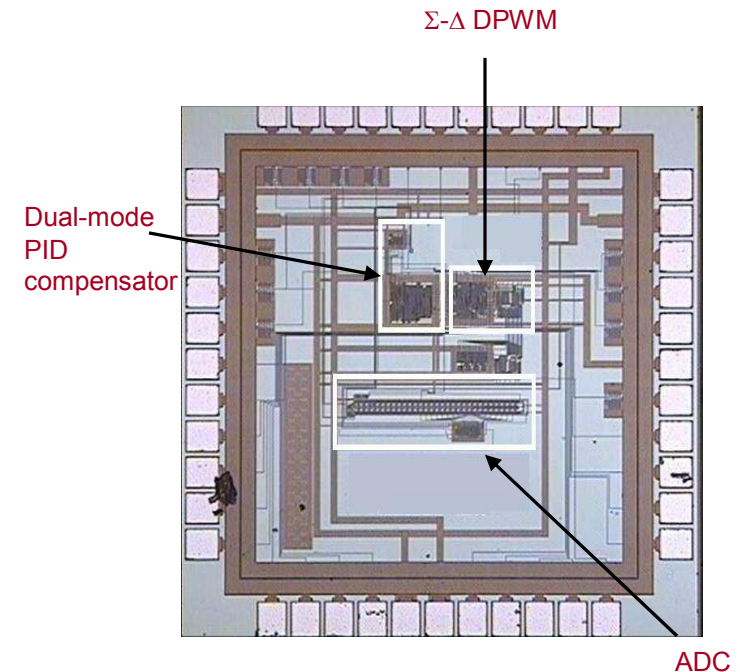
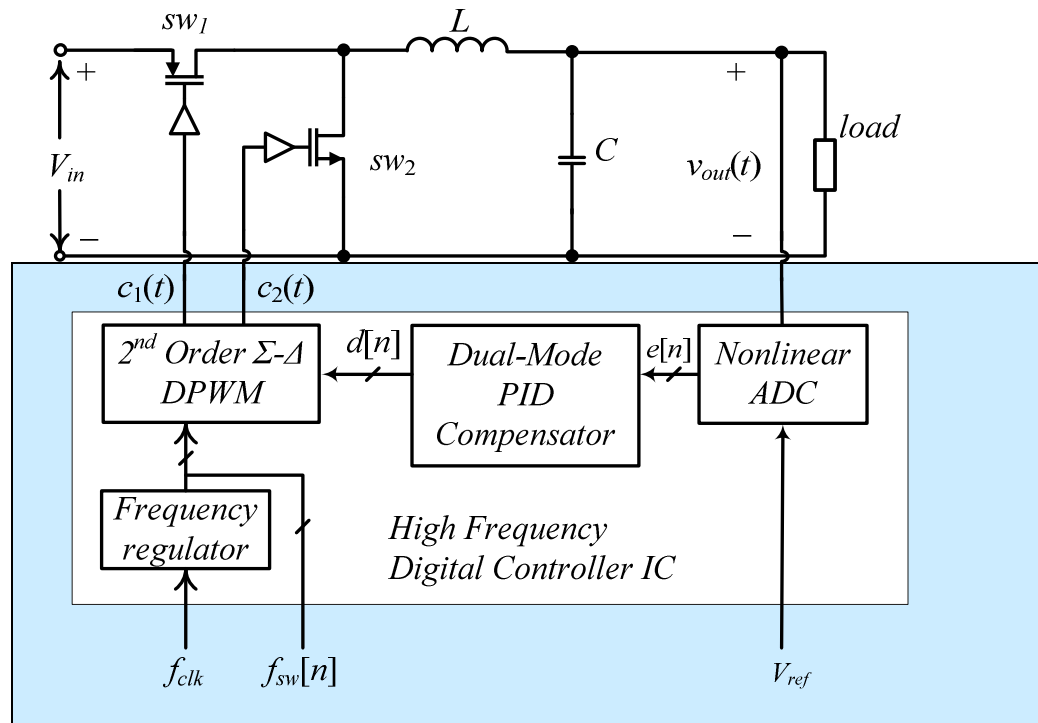


Mixed-signal controller enables system integration through:

- *Operation at ultra high switching frequencies*
- *Minimum deviation response to load transients (Cap sized based on transients)*
- *Interaction with the load, ideally, allowing C to be sized based on ripple only*



Ultra-High Frequency Digital Controller



Digital controller supporting operation at switching frequencies of several hundreds of MHz is available ^[1]

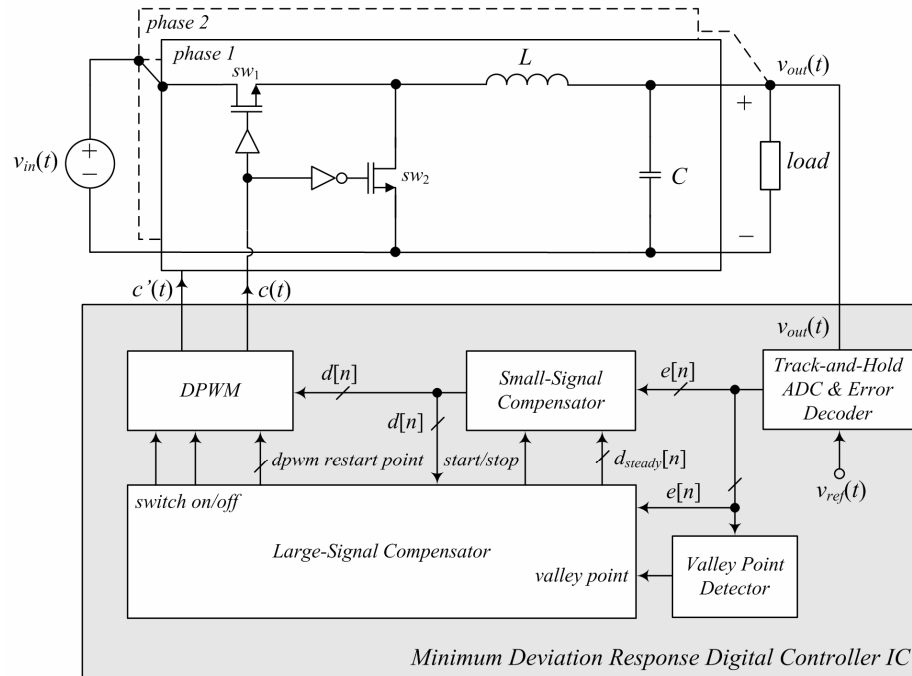


[1] Z. Lukić, N. Rahman, and A. Prodić, "Multi-Bit Sigma-Delta PWM Digital Controller IC for DC-DC Converters Operating at

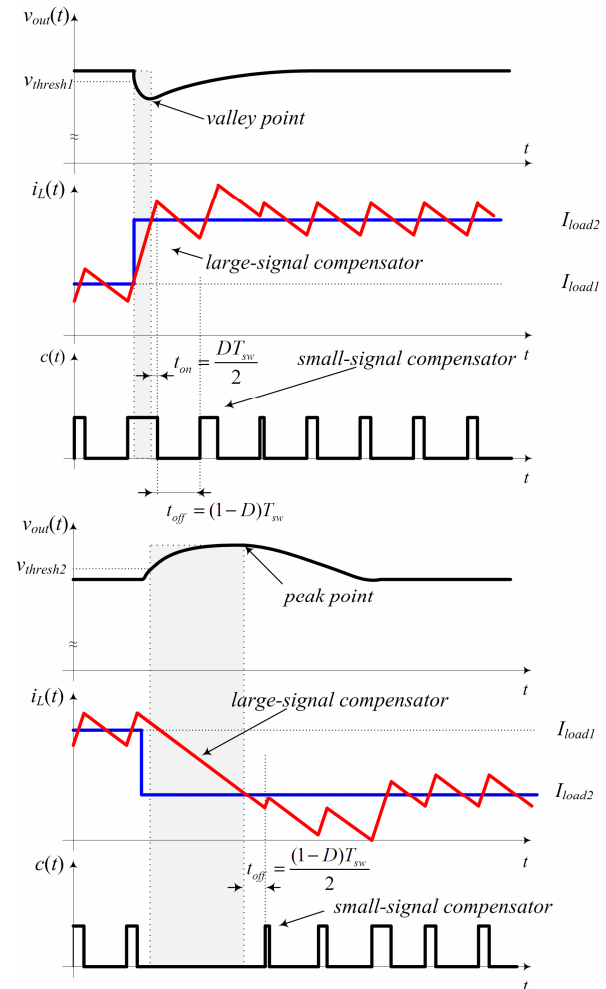
Switching Frequencies Beyond 10 MHz," IEEE Transactions on Power Electronics, September 2007, Vol.22, Issue 5, pp. 1693-1707

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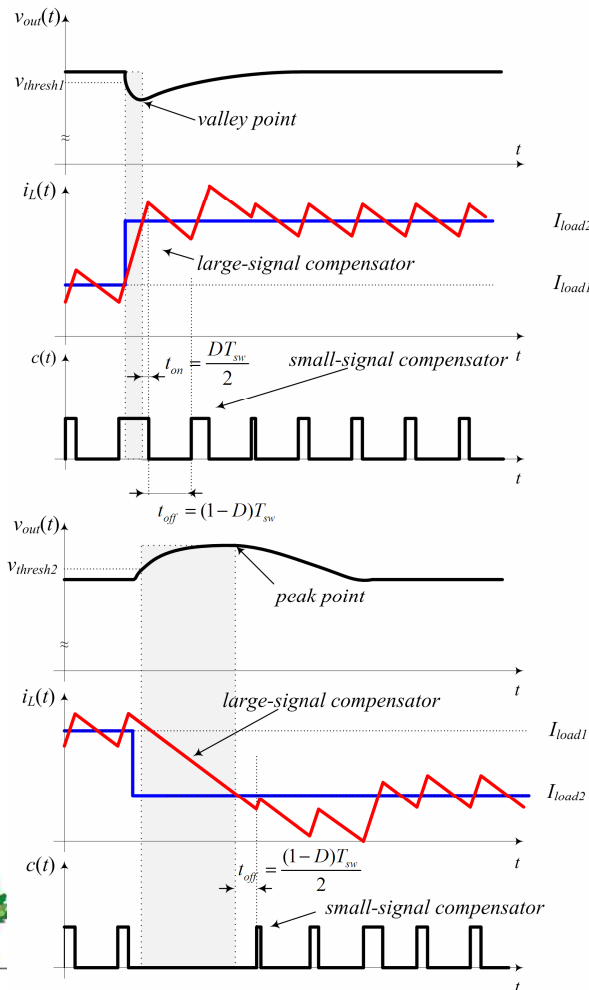
Minimum (Optimum) Deviation Controller



- Operates on principle that is not directly BW related
- Requires no knowledge of power stage parameters
- Minimizes current stress



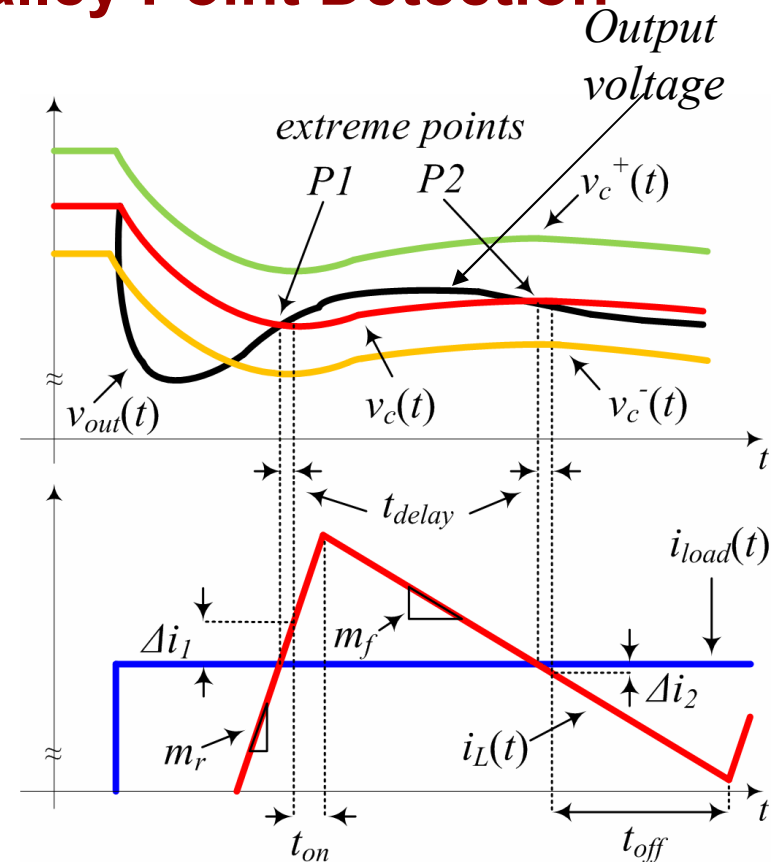
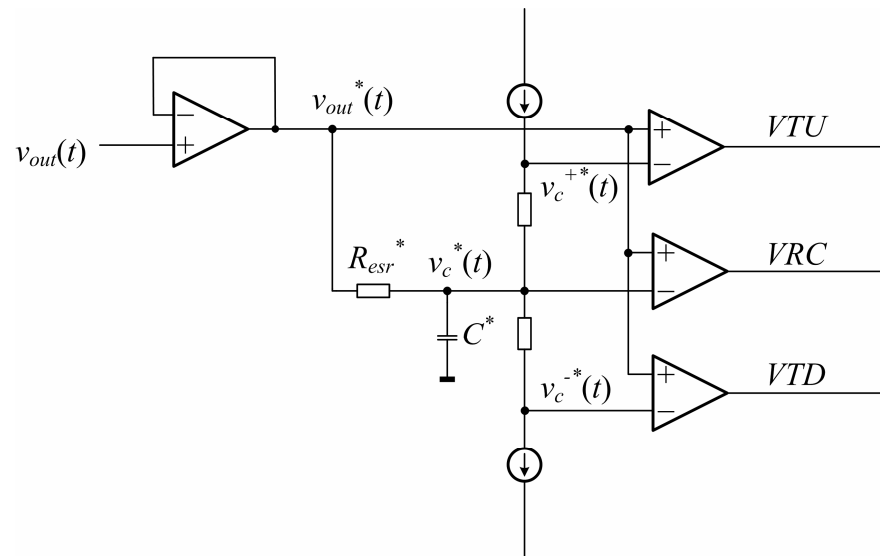
Practical Implementation Challenges



- *Accurate and fast detection of transient and valley points is required*
- *Mode transition stability problems due to mismatch in pre and post transient steady state duty ratio values*



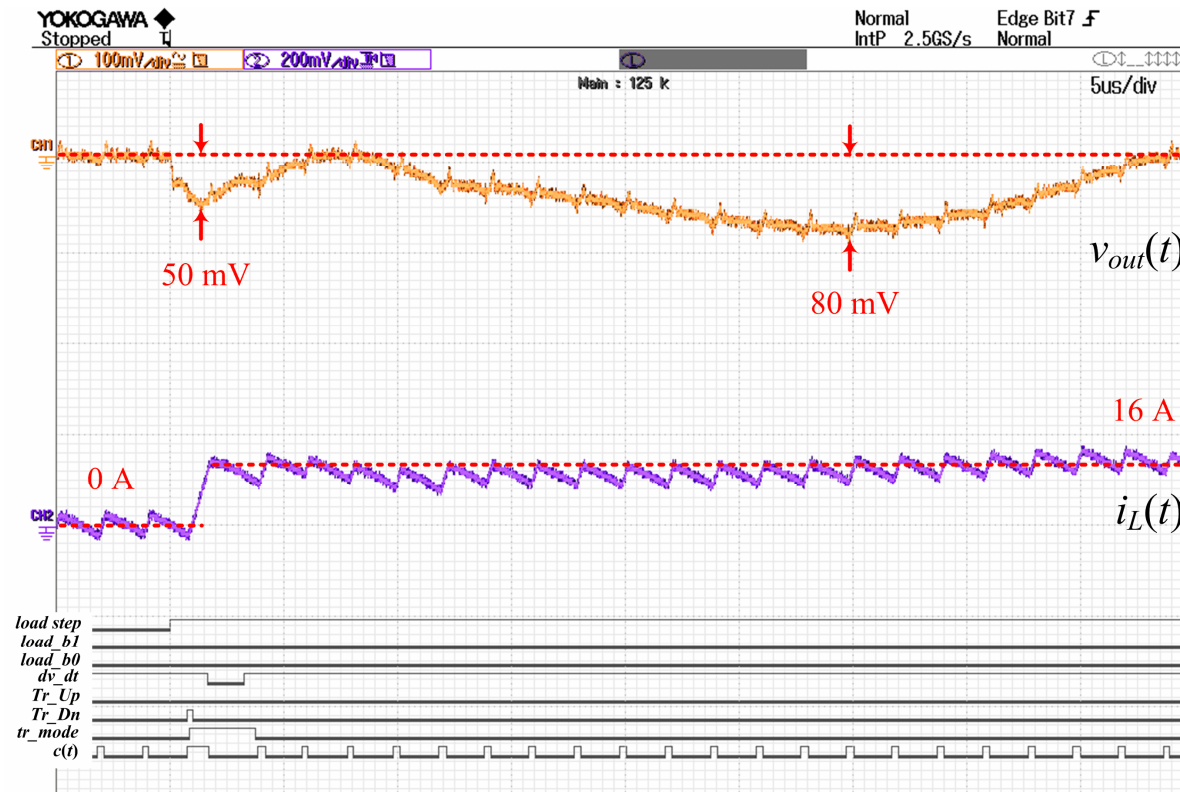
Load Transient and Dual Valley Point Detection



- Two comparators form a no-loaded capacitor window around steady state value
- Dual-valley point detection performed to minimize error



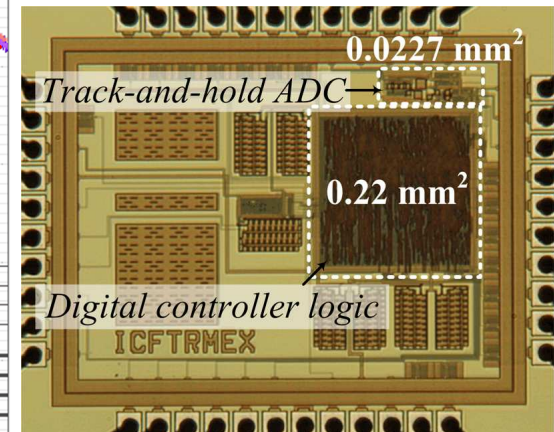
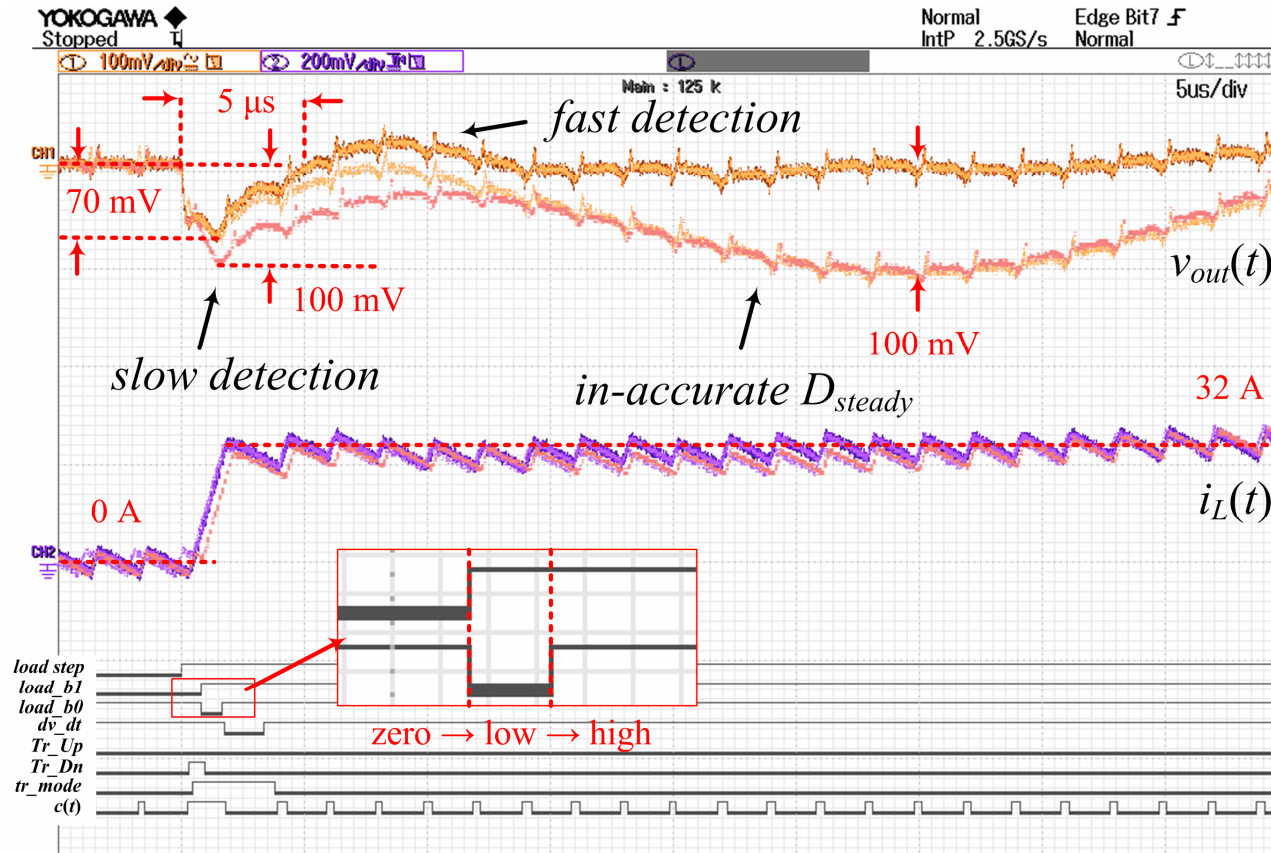
Duty Ratio Value Correction



- Due to D mismatch even for a highly efficient converter a deviation larger than that due to the transient can occur



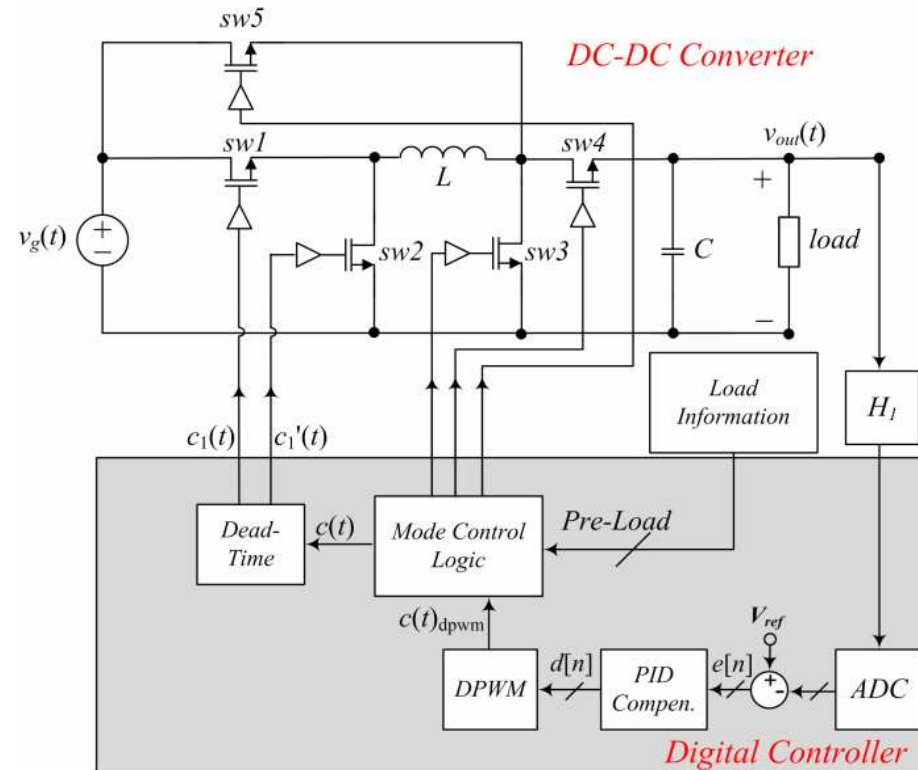
Controller Response & On-Chip Implementation



- Physical limit of a given power stage, about 4 x smaller cap compared to 1/10 PID
- Simpler implementation than time-optimal + no knowledge of parameters needed



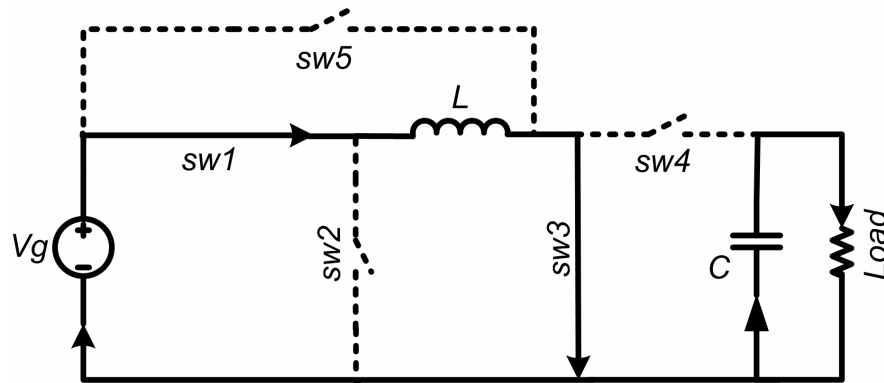
Load Interactive Digitally Controlled SMPS



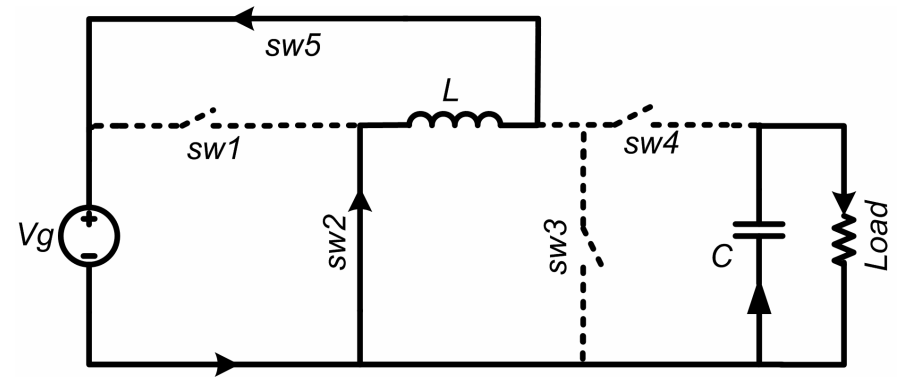
- *Non-inverting buck-boost power stage modified with an addition of extra switch (recycling switch)*
- *Communication with the load giving a pre-load command established to pre-charge inductor to a value closer to the new load current prior the transient*



Pre-Load/ Post-Load Conditions



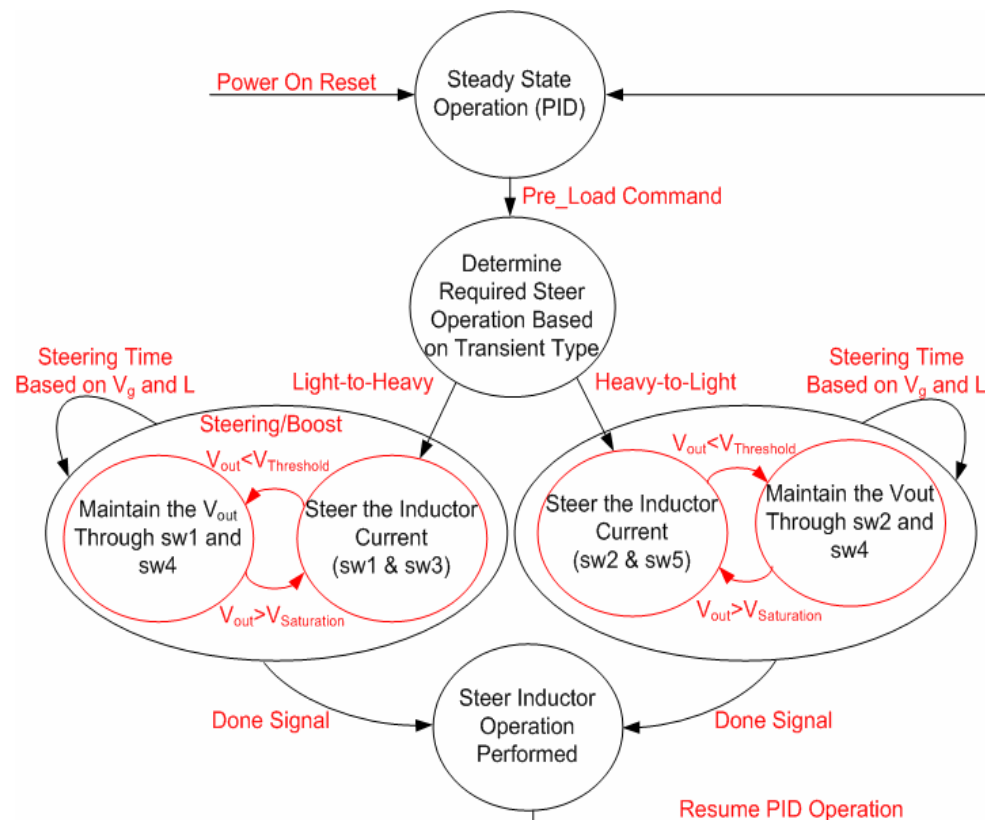
- *Light-to-heavy pre-load*



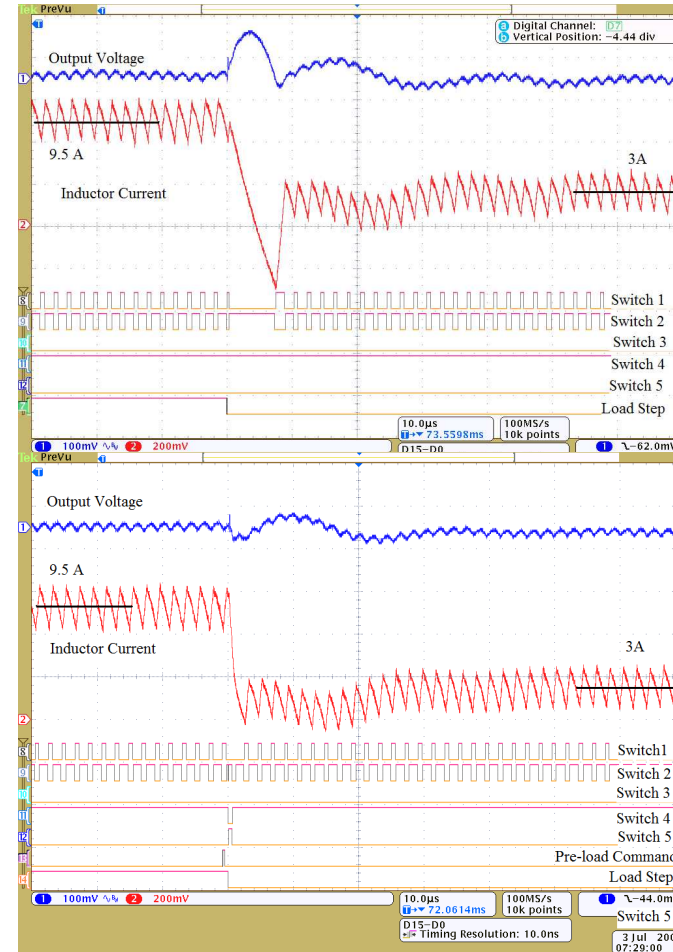
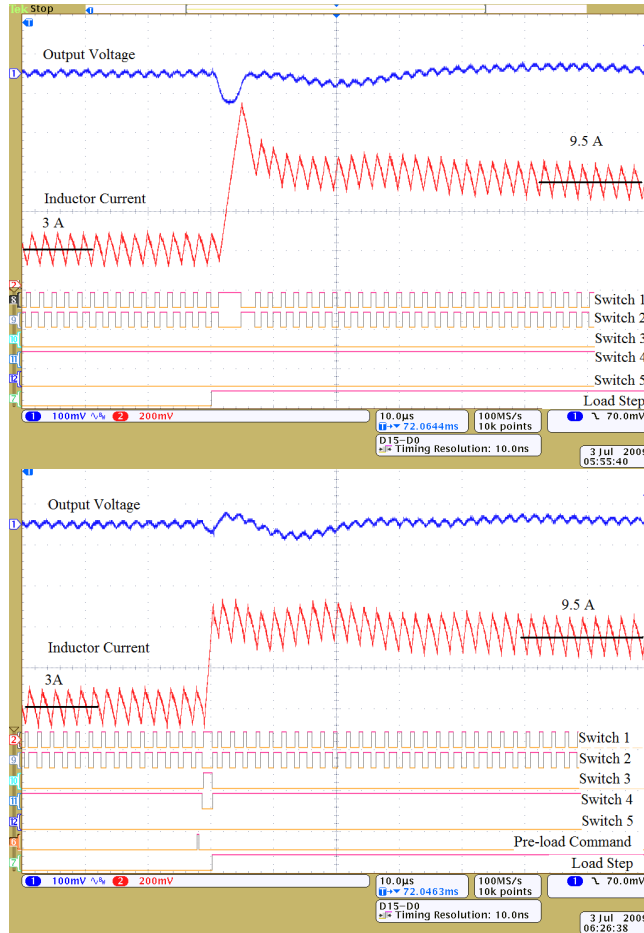
- *Heavy-to-light post-load*



Control Algorithm



Transient Performance



- *Top: time-optimal*
- *Bottom: load-interactive (theoretically allowing reduction limited by ripple only) only*

Conclusion

- *Mixed signal control methods can bring us few steps closer to a full on-chip implementation of SMPS, potentially allowing output capacitor and inductor to be sized based on physical limitation of the converter or even on the ripple requirements only*
- *Better interconnection with loads can potentially result in about 25% reduction of the overall system size including both power supplies and the supplied devices*

